

The components of strain at a point are given by

$$[\varepsilon_{ij}] = 10^{-4} \begin{bmatrix} 1 & -3 & \sqrt{2} \\ -3 & 1 & -\sqrt{2} \\ \sqrt{2} & -\sqrt{2} & 4 \end{bmatrix}.$$

The vectors \mathbf{m} and \mathbf{n} are defined by $\mathbf{m} = -\mathbf{e}_1 + \mathbf{e}_2 + \sqrt{2}\mathbf{e}_3$ and $\mathbf{n} = \mathbf{e}_1 - \mathbf{e}_2 + \sqrt{2}\mathbf{e}_3$.

- Determine the normal strain in the direction of the vector \mathbf{n} .
- Determine the shear strain in the direction of \mathbf{m} on the plane with a normal \mathbf{n} .
- Determine the principal strains.
- Determine the principal strain directions.

The transformation rule for changing strain components under rotation of axes is

$$\varepsilon_{ij}^* = Q_{ip}Q_{jq}\varepsilon_{pq} = \sum_{p=1}^3 \sum_{q=1}^3 Q_{ip}Q_{jq}\varepsilon_{pq} \text{ where } Q_{ij} = \mathbf{e}_i^* \cdot \mathbf{e}_j \text{ and } \mathbf{e}_i^*, \mathbf{e}_j \text{ are base vectors.}$$